## Review of Lecture 6

- $m_{\mathcal{H}}(N)$ is polynomial
if $\mathcal{H}$ has a break point $k$

- The VC Inequality

Hoeffding Inequality

(a)

(b)

VC Bound

(c)

$$
\begin{array}{rlcc}
\mathbb{P}\left[\left|E_{\text {in }}(g)-E_{\text {out }}(g)\right|>\epsilon\right] \leq & 2 & M & e^{-2 \epsilon^{2} N} \\
& \downarrow & \downarrow & \downarrow \\
& \downarrow & \downarrow & \downarrow \\
\mathbb{P}\left[\left|E_{\text {in }}(g)-E_{\text {out }}(g)\right|>\epsilon\right] \leq & 4 & m_{\mathcal{H}}(2 N) & e^{-\frac{1}{8} \epsilon^{2} N}
\end{array}
$$

# Learning From Data 

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## Lecture 7: The VC Dimension

## Outline

- The definition
- VC dimension of perceptrons
- Interpreting the VC dimension
- Generalization bounds


## Definition of VC dimension

The VC dimension of a hypothesis set $\mathcal{H}$, denoted by $d_{\mathrm{VC}}(\mathcal{H})$, is
the largest value of $N$ for which $m_{\mathcal{H}}(N)=2^{N}$
"the most points $\mathcal{H}$ can shatter"

$$
\begin{aligned}
N \leq d_{\mathrm{VC}}(\mathcal{H}) & \Longrightarrow \mathcal{H} \text { can shatter } N \text { points } \\
k>d_{\mathrm{VC}}(\mathcal{H}) & \Longrightarrow k \text { is a break point for } \mathcal{H}
\end{aligned}
$$

## The growth function

In terms of a break point $k$ :

$$
m_{\mathcal{H}}(N) \leq \sum_{i=0}^{k-1}\binom{N}{i}
$$

In terms of the VC dimension $d_{\mathrm{VC}}$ :

$$
m_{\mathcal{H}}(N) \leq \underbrace{\sum_{i=0}^{d_{\mathrm{VC}}}\binom{N}{i}}_{\text {maximum power is }}
$$

## Examples

- $\mathcal{H}$ is positive rays:

$$
d_{\mathrm{VC}}=1
$$

- $\mathcal{H}$ is 2 D perceptrons:

$$
d_{\mathrm{VC}}=3
$$

- $\mathcal{H}$ is convex sets:

$$
d_{\mathrm{VC}}=\infty
$$

## VC dimension and learning

$d_{\mathrm{VC}}(\mathcal{H})$ is finite $\quad \Longrightarrow \quad g \in \mathcal{H}$ will generalize

- Independent of the learning algorithm
- Independent of the input distribution


PROBABILITY
distribution
$P$ on $X$
TRAINING EXAMPLES
$\left(\mathbf{x}_{1}, y_{1}\right), \ldots,\left(\mathbf{x}_{N}, y_{N}\right)$ LEARNING
ALGORITHM

- Independent of the target function $\square$


## VC dimension of perceptrons

For $d=2, d_{\mathrm{VC}}=3$
In general, $\quad d_{\mathrm{VC}}=d+1$

We will prove two directions:

$$
\begin{aligned}
& d_{\mathrm{VC}} \leq d+1 \\
& d_{\mathrm{VC}} \geq d+1
\end{aligned}
$$



## Here is one direction

A set of $N=d+1$ points in $\mathbb{R}^{d}$ shattered by the perceptron:

$$
\mathrm{X}=\left[\begin{array}{c}
-\mathbf{x}_{1}^{\top}- \\
-\mathbf{x}_{2}^{\top}- \\
-\mathbf{x}_{3}^{\top}- \\
\vdots \\
-\mathbf{x}_{d+1}^{\top}-
\end{array}\right]=\left[\begin{array}{ccccc}
1 & 0 & 0 & \ldots & 0 \\
1 & 1 & 0 & \ldots & 0 \\
1 & 0 & 1 & & 0 \\
& \vdots & & \ldots & 0 \\
1 & 0 & \ldots & 0 & 1
\end{array}\right]
$$

X is invertible

## Can we shatter this data set?

For any $\mathbf{y}=\left[\begin{array}{c}y_{1} \\ y_{2} \\ \vdots \\ y_{d+1}\end{array}\right]=\left[\begin{array}{c} \pm 1 \\ \pm 1 \\ \vdots \\ \pm 1\end{array}\right]$, can we find a vector $\mathbf{w}$ satisfying

$$
\operatorname{sign}(X w)=\mathbf{y}
$$

Easy! Just make $\quad \mathrm{Xw}=\mathbf{y}$
which means $\quad \mathbf{w}=X^{-1} \mathbf{y}$

## We can shatter these $d+1$ points

This implies what?

$$
[\mathrm{a}] d_{\mathrm{VC}}=d+1
$$

$$
[\mathrm{b}] d_{\mathrm{VC}} \geq d+1
$$

$$
[\mathrm{c}] d_{\mathrm{VC}} \leq d+1
$$

[d] No conclusion

Now, to show that $d_{\mathrm{vc}} \leq d+1$

## We need to show that:

[a] There are $d+1$ points we cannot shatter
[b] There are $d+2$ points we cannot shatter
[c] We cannot shatter any set of $d+1$ points
[d] We cannot shatter any set of $d+2$ points

## Take any $d+2$ points

For any $d+2$ points,

$$
\mathbf{x}_{1}, \cdots, \mathbf{x}_{d+1}, \mathbf{x}_{d+2}
$$

More points than dimensions $\Longrightarrow$ we must have

$$
\mathbf{x}_{j}=\sum_{i \neq j} a_{i} \mathbf{x}_{i}
$$

where not all the $a_{i}$ 's are zeros

## So?

$$
\mathbf{x}_{j}=\sum_{i \neq j} a_{i} \mathbf{x}_{i}
$$

Consider the following dichotomy:
$\mathbf{x}_{i}$ 's with non-zero $a_{i}$ get $\quad y_{i}=\operatorname{sign}\left(a_{i}\right)$
and $\mathbf{x}_{j}$ gets $y_{j}=-1$

No perceptron can implement such dichotomy!

## Why?

$$
\mathbf{x}_{j}=\sum_{i \neq j} a_{i} \mathbf{x}_{i} \quad \Longrightarrow \quad \mathbf{w}^{\top} \mathbf{x}_{j}=\sum_{i \neq j} a_{i} \mathbf{w}^{\top} \mathbf{x}_{i}
$$

If $y_{i}=\operatorname{sign}\left(\mathbf{w}^{\top} \mathbf{x}_{i}\right)=\operatorname{sign}\left(a_{i}\right)$, then $a_{i} \mathbf{w}^{\top} \mathbf{x}_{i}>0$

This forces

$$
\mathbf{w}^{\top} \mathbf{x}_{j}=\sum_{i \neq j} a_{i} \mathbf{w}^{\top} \mathbf{x}_{i}>0
$$

Therefore, $\quad y_{j}=\operatorname{sign}\left(\mathbf{w}^{\top} \mathbf{x}_{j}\right)=+1$

## Putting it together

We proved $\quad d_{\mathrm{VC}} \leq d+1 \quad$ and $\quad d_{\mathrm{VC}} \geq d+1$

$$
d_{\mathrm{VC}}=d+1
$$

What is $d+1$ in the perceptron?

It is the number of parameters $w_{0}, w_{1}, \cdots, w_{d}$

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## 1. Degrees of freedom

Parameters create degrees of freedom
\# of parameters: analog degrees of freedom
$d_{\mathrm{VC}}$ : equivalent 'binary' degrees of freedom


## The usual suspects

Positive rays $\left(d_{\mathrm{VC}}=1\right)$ :

$$
h(x)=-1 \quad \begin{array}{lll} 
& & \\
\end{array}
$$

Positive intervals $\left(d_{\mathrm{VC}}=2\right)$ :

$$
h(x)=-1 \quad h(x)=+1 \quad h(x)=-1
$$

## Not just parameters

Parameters may not contribute degrees of freedom:

$d_{\mathrm{VC}}$ measures the effective number of parameters

## 2. Number of data points needed

Two small quantities in the VC inequality:

$$
\mathbb{P}\left[\left|E_{\text {in }}(g)-E_{\text {out }}(g)\right|>\epsilon\right] \leq \underbrace{4 m_{\mathcal{H}}(2 N) e^{-\frac{1}{8} \epsilon^{2} N}}_{\delta}
$$

If we want certain $\epsilon$ and $\delta$, how does $N$ depend on $d_{\mathrm{VC}}$ ?

Let us look at

$$
N^{d} e^{-N}
$$

$$
N^{d} e^{-N}
$$

Fix $N^{d} e^{-N}=$ small value

How does $N$ change with $d$ ?

## Rule of thumb:

$$
N \geq 10 d_{\mathrm{VC}}
$$



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## Rearranging things

Start from the VC inequality:

$$
\mathbb{P}\left[\left|E_{\text {out }}-E_{\text {in }}\right|>\epsilon\right] \leq \underbrace{4 m_{\mathcal{H}}(2 N) e^{-\frac{1}{8} \epsilon^{2} N}}_{\delta}
$$

Get $\epsilon$ in terms of $\delta$ :

$$
\delta=4 m_{\mathcal{H}}(2 N) e^{-\frac{1}{8} \epsilon^{2} N} \Longrightarrow \epsilon=\underbrace{\sqrt{\frac{8}{N} \ln \frac{4 m_{\mathcal{H}}(2 N)}{\delta}}}_{\Omega}
$$

With probability $\geq 1-\delta$,

$$
\left|E_{\text {out }}-E_{\text {in }}\right| \leq \Omega(N, \mathcal{H}, \delta)
$$

## Generalization bound

With probability $\geq 1-\delta, \quad E_{\text {out }}-E_{\text {in }} \leq \Omega$


$$
\text { With probability } \geq 1-\delta
$$

$$
E_{\text {out }} \leq E_{\text {in }}+\Omega
$$

